

Real-valued function:

$$\text{If } f : \mathbf{R}^n \rightarrow \mathbf{R}, \text{ then } Df = \nabla f = \left(\frac{\partial f}{\partial x_1} \dots \frac{\partial f}{\partial x_n} \right)$$

Ch 3: Path in \mathbf{R}^n :

$$\text{If } \mathbf{x} : I \subset \mathbf{R} \rightarrow \mathbf{R}^n, \text{ then } D\mathbf{x} = [\mathbf{x}'(t)]^T$$

If \mathbf{x} represents position,

$$\mathbf{v}(t) = \mathbf{x}'(t) = \text{velocity vector and}$$

$$\mathbf{a}(t) = \mathbf{v}'(t) = \mathbf{x}''(t) = \text{acceleration vector.}$$

$$\text{Speed of path} = \|\mathbf{x}'(t)\|$$

If $x : [a, b] \rightarrow \mathbf{R}^n$, then

$$\text{length of path} = L(\mathbf{x}) = \int_a^b \|\mathbf{x}'(t)\| dt$$

$$\text{Arclength parameter} = s : [a, b] \rightarrow [0, L(\mathbf{x})], \blacksquare$$

$$s(t) = \int_a^t \|\mathbf{x}'(u)\| du$$

Example: $\mathbf{x} : [10, 100] \rightarrow \mathbf{R}^2, \mathbf{x}(t) = (t, 4t)$

velocity vector = $\mathbf{v}(t) = \mathbf{x}'(t) = (1, 4)$ and

acceleration vector = $\mathbf{a}(t) = \mathbf{v}'(t) = \mathbf{x}''(t) = (0, 0)$

$$\text{Speed} = \|\mathbf{x}'(t)\| = \|(1, 4)\| = \sqrt{1^2 + 4^2} = \sqrt{17}$$

$$\text{length of path} = L(\mathbf{x}) = \int_{10}^{100} \|\mathbf{x}'(t)\| dt = \int_{10}^{100} \sqrt{17} dt \blacksquare$$

$$= \sqrt{17}t \Big|_{10}^{100} = \sqrt{17}(100 - 10) = 90\sqrt{17}$$

Arclength parameter = $s : [10, 100] \rightarrow [0, 90\sqrt{17}]$,

$$s(t) = \int_{10}^t \sqrt{17} du = \sqrt{17}u \Big|_{10}^t = \sqrt{17}(t - 10)$$

Thus $s : [10, 100] \rightarrow [0, 90\sqrt{17}]$,

$$s(t) = t\sqrt{17} - 10\sqrt{17}$$

Change of parametrization:

Solve for t to find s^{-1} : $t = \frac{s+10\sqrt{17}}{\sqrt{17}}$.

Let the function s^{-1} be denoted by t

Hence $t : [0, 90\sqrt{17}] \rightarrow [10, 100]$, $t(s) = \frac{s+10\sqrt{17}}{\sqrt{17}}$

$\mathbf{y} : [0, 90\sqrt{17}] \rightarrow \mathbf{R}^2$, $\mathbf{y}(s) = (\mathbf{x} \circ t)(s)$

$$\mathbf{y}(s) = \mathbf{x}(t(s)) = \mathbf{x}\left(\frac{s+10\sqrt{17}}{\sqrt{17}}\right) = \left(\frac{s+10\sqrt{17}}{\sqrt{17}}, 4\left(\frac{s+10\sqrt{17}}{\sqrt{17}}\right)\right) \blacksquare$$

Thus the reparametrization of the path \mathbf{x} using the arclength parameter s is

$$\mathbf{y} : [0, 90\sqrt{17}] \rightarrow \mathbf{R}^2, \mathbf{y}(s) = \left(\frac{s+10\sqrt{17}}{\sqrt{17}}, 4\left(\frac{s+10\sqrt{17}}{\sqrt{17}}\right)\right)$$

Observe $\|\mathbf{y}'(s)\| = 1$ and the length of the path traveled by time s is $\int_0^s \|\mathbf{y}'(u)\| du = s$

Unit tangent vector: $\mathbf{T}(t) = \frac{\mathbf{x}'(t)}{\|\mathbf{x}'(t)\|}$

Note $\mathbf{T}(t)$ is perpendicular to $\mathbf{T}'(t)$

outline of proof: Use $\frac{d}{dt} \|\mathbf{T}(t)\|^2 = \frac{d}{dt}(1)$
to show $\mathbf{T}(t) \cdot \mathbf{T}'(t) = 0$

Let unit normal vector = $\mathbf{N} = \frac{\mathbf{T}'(t)}{\|\mathbf{T}'(t)\|}$

Let unit binormal vector $\mathbf{B} = \mathbf{T} \times \mathbf{N}$.

Note \mathbf{B} is a unit vector.

$\mathbf{T}(t)$, $\mathbf{N}(t)$, $\mathbf{B}(t)$ is a set of mutually orthogonal unit vectors called the moving frame (or Frenet frame).

Curvature $\kappa = \left\| \frac{d\mathbf{T}}{ds} \right\| = \frac{\left\| \frac{d\mathbf{T}}{dt} \right\|}{\frac{ds}{dt}}$

Torsion $\tau = \left\| \frac{d\mathbf{B}}{ds} \right\| = \frac{\left\| \frac{d\mathbf{B}}{dt} \right\|}{\frac{ds}{dt}} = \tau \mathbf{N}$

Intrinsic quantity: does **NOT** depend on parametrization: \blacksquare

Ex: \mathbf{T} , \mathbf{N} , \mathbf{B} , κ , τ , length of path.

Extrinsic quantity: depends on parametrization:

Ex: speed, velocity, acceleration